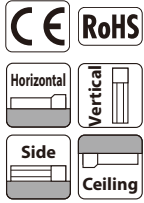


RCP6(S)-RA7C

Battery-less Absolute
Motor Unit Type
Coupled Motor
Body Width 70 mm
24v Stepper Motor

Model Specification Items	Series	Type	Encoder Type	Motor Type	Lead	Stroke	Applicable Controller/I/O Type	Cable Length	Options
	RA7C	WA	56P						
	RCP6: Separate Controller RCP6S: Built-in Controller	WA: Battery-less Absolute	56P: Stepper Motor 56□ Size	24: 24mm 16: 16mm 8: 8mm 4: 4mm	50: 50mm 300: 300mm (50mm increments)	[RCP6] P3: PCON MCON MSEL [RCP6S] SE: SIO Type	N : None P : 1m S : 3m M : 5m X□□ : Specified Length R□□ : Robot Cable	Please refer to the options table below.	

* RCP6 does not include a controller. RCP6S includes a built-in controller.
* Please refer to P.11 for more information about the model specification items.



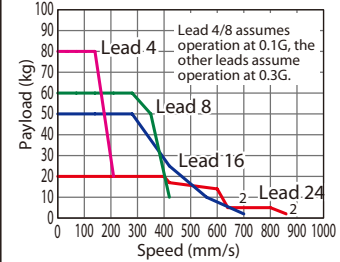
*Depending on the model, there may be some limitations to using the vertical, side, and ceiling mount positions. Please contact IAI for more information regarding mounting positions.



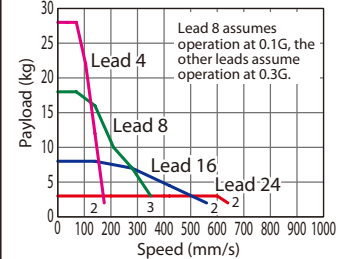
- The maximum acceleration/deceleration is 1G for horizontal, and 0.5G for vertical use.
- The actuator specification displays the payload's maximum value, but it will vary depending on the acceleration and speed. Please refer to the "Selection Guidelines" (RCP6 Tables of Payload by Speed/Acceleration) on P.115 for more details.
- The value of the horizontal payload assumes that there is an external guide. Please be aware that the anti-rotation stopper can be damaged when an external force is applied to the rod from any direction other than the moving direction.
- When performing push-motion operation, please confirm the push force of each model by checking the "Correlation diagram of push force and current limit" on P.113.
- Depending on the ambient operational temperature, duty control is necessary for the RCP6S (built-in controller type) with lead 4/8/16. Please refer to P.130 for more information.

Correlation Diagrams of Speed and Payload

High-output enabled with PCON/MCON/MSEL connected.
RCP6(S)-RA7C Horizontal mount



RCP6(S)-RA7C Vertical mount



Actuator Specifications

Lead and Payload

Model Number	Lead (mm)	Connected Controller	Max. Payload		Stroke (mm)
			Horizontal (kg)	Vertical (kg)	
RCP6(S)-RA7C-WA-56P-24-①-②-③-④	24	High-output Enabled	20	3	50~300 (The increment of stroke is 50mm)
RCP6(S)-RA7C-WA-56P-16-①-②-③-④	16	High-output Enabled	50	8	
RCP6(S)-RA7C-WA-56P-8-①-②-③-④	8	High-output Enabled	60	18	
RCP6(S)-RA7C-WA-56P-4-①-②-③-④	4	High-output Enabled	80	28	

Legend: ① Stroke ② Applicable controller/I/O type ③ Cable length ④ Options

Stroke and Max. Speed

(Unit: mm/s)

Lead (mm)	Connected Controller	50~300 (Every 50mm)
24	High-output Enabled	860 <640>
16	High-output Enabled	700 <560>
8	High-output Enabled	420 <350>
4	High-output Enabled	210 <175>

Values in brackets < > are for vertical use.

① Stroke

Stroke (mm)	RCP6	RCP6S	Stroke (mm)	RCP6	RCP6S
50	○	○	200	○	○
100	○	○	250	○	○
150	○	○	300	○	○

④ Options

Name	Option Code	Reference Page
Brake	B	See P.105
Cable exit direction (Top)	CJT	See P.105
Cable exit direction (Right)	CJR	See P.105
Cable exit direction (Left)	CJL	See P.105
Cable exit direction (Bottom)	CJB	See P.105
Flange	FL	See P.106
Foot bracket	FT	See P.107
Tip adapter (Internal thread)	NFA	See P.109
Non-motor end specification	NM	See P.110
T-slot nut bar	NTB	See P.110

When selecting multiple options, please list them in alphabetical order. (e.g. B-CJB-NM)

③ Cable Length

Cable Type	Cable Code	RCP6	RCP6S
Standard	P (1m)	○	○
	S (3m)	○	○
	M (5m)	○	○
Specified Length	X06 (6m) ~X10 (10m)	○	○
	X11 (11m) ~X15 (15m)	○	○
	X16 (16m) ~X20 (20m)	○	○
	R01 (1m) ~R03 (3m)	○	○
Robot Cable	R04 (4m) ~R05 (5m)	○	○
	R06 (6m) ~R10 (10m)	○	○
	R11 (11m) ~R15 (15m)	○	○
	R16 (16m) ~R20 (20m)	○	○

* Please refer to P.144 for more information regarding the maintenance cables.

Actuator Specifications

Item	Description
Drive system	Ball screw φ12mm, rolled C10
Positioning repeatability	±0.01mm
Lost motion	0.1mm or less
Rod	φ30mm Material: Aluminum with hard alumite treatment
Static allowable torque on rod tip	2.5N·m
Max. angular displacement on rod tip (*1)	±0.8 deg.
Ambient operating temp. & humidity	0~40°C, 85% RH or less (Non-condensing)

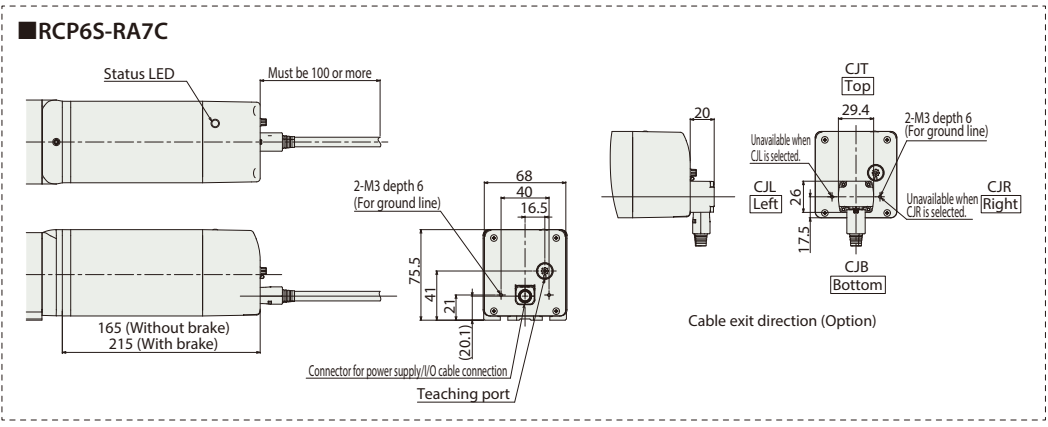
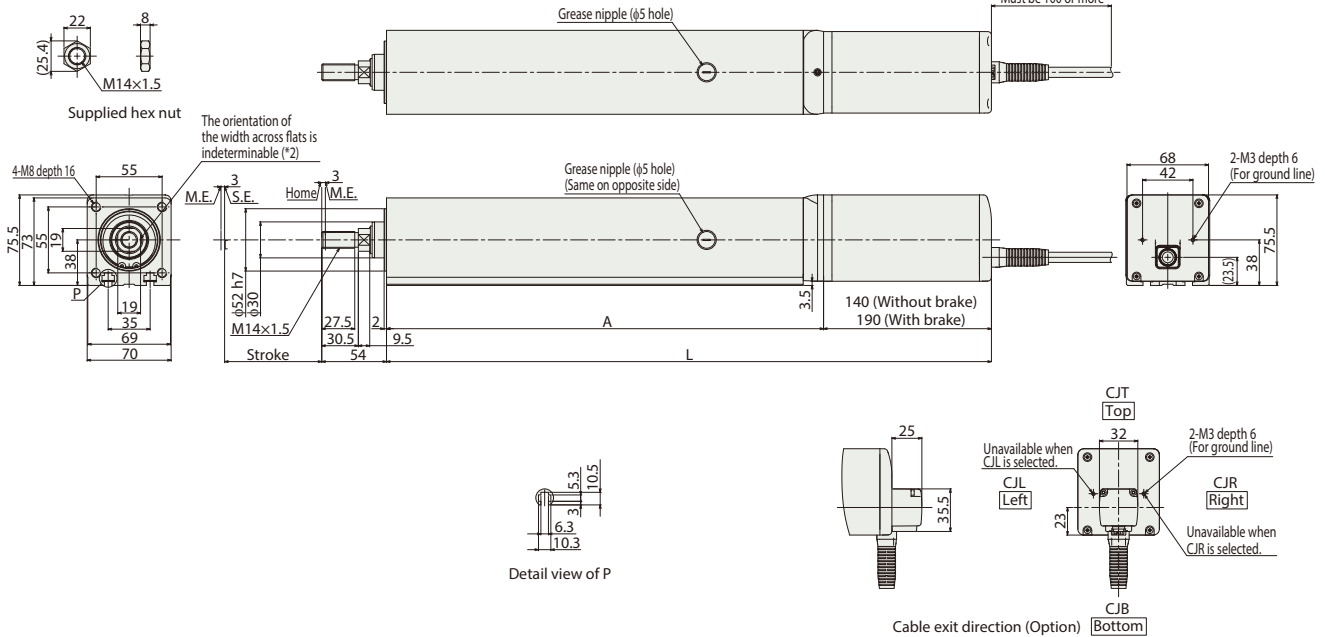
(*1) This is the displacement angle of the rod tip (initial reference value) when the rod is fully retracted and the static allowable torque is applied at the rod tip.

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.com



*1 When the rod is returning to its home position, please be careful of interference from surrounding objects, as it will travel until it reaches the M.E.
M.E: Mechanical end S.E: Stroke end
*2 The direction of width across flats varies depending on the product.



■ Dimensions and Mass by Stroke

		Stroke	50	100	150	200	250	300
L	RCP6	w/o brake	354.5	404.5	454.5	504.5	554.5	604.5
		w/ brake	404.5	454.5	504.5	554.5	604.5	654.5
	RCP6S	w/o brake	379.5	429.5	479.5	529.5	579.5	629.5
		w/ brake	429.5	479.5	529.5	579.5	629.5	679.5
A			214.5	264.5	314.5	364.5	414.5	464.5
Mass (kg)	RCP6	w/o brake	4.5	5.1	5.6	6.2	6.7	7.3
		w/ brake	4.9	5.5	6.0	6.6	7.2	7.7
	RCP6S	w/o brake	4.7	5.2	5.8	6.3	6.9	7.5
		w/ brake	5.1	5.7	6.2	6.8	7.3	7.9

② Applicable Controllers

The RCP6 series actuators can be operated by the controllers indicated below. Please select the type depending on your intended use. * Please refer to P.147 for more information about the built-in controller of RCP6S series.

Name	External view	Max. number of controlled axes	Input power	Control method				Maximum number of positioning points	Reference page
				Positioner	Pulse train	Program	Network *Option		
PCON-CB/CGB		1	DC24V	● *Option	● *Option	-	 Note: The type of compatible networks will vary depending on the controller. Please refer to reference page for more information.	512 (768 for network spec.)	Please see P.131
MCON-C/CG		4		This model is network-compatible only.					
MSEL-PC/PG		4	Single-phase 100~230VAC	-	-	●		30,000	Please see the MSEL-PC/PG catalog.

* Please select "high-output specification" as an option for the MCON. With the MCON, operation is possible only when the high-output specification is selected.